

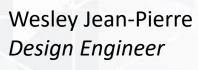
JTEKT Bearing Painter VDR 6

Senior Design Team 515

Team Introductions



Mason Gibson Manufacturing Engineer

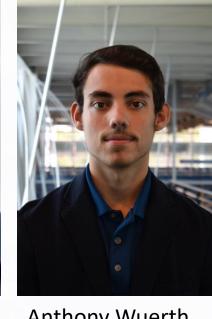


Max Jones Project Manager & Control Engineer

Andrew McClung Systems Integration Engineer

Anthony Wuerth Manufacturing & Design Engineer





Sponsors and Advisor



Engineering Mentor Coltin Fortner *Mechanical Engineer JTEKT North America*





Engineering Mentor Joshua Jones Senior Product Engineer JTEKT North America



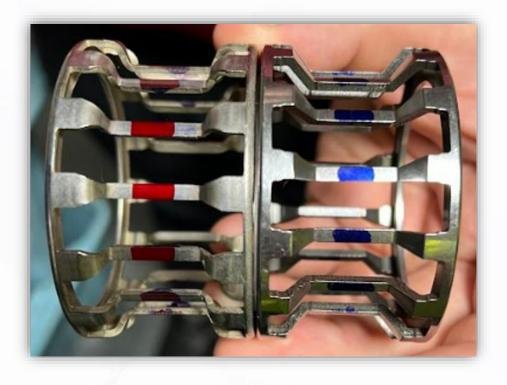


<u>Academic Advisor</u> Shayne McConomy, Ph.D. Senior Design Professor



FAMU-FSU College of Engineering





Project Objective

The objective of this project is to automate the process of painting needle bearing retainers.



Project Overview

Maximilian Jones



Background

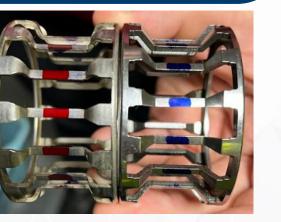
- Creates line contact using rollers
- Commonly used in \bullet transmissions
- The retainer houses the rollers

Paint is used by \bullet customers to identify different parts







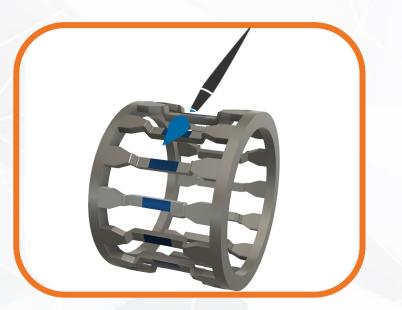


- Currently hand- \bullet painted under a fume hood
- Roughly 200 are ulletneeded per month but this may be increasing





Key Goals







Accurately Apply Metal Paint to the Bearing Accommodate Bearings from 7/8-2 ½ in. (Outer Diameter)

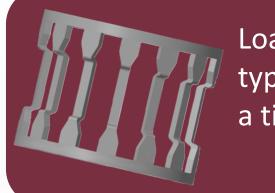
Automate Bearing Painting Process



Max Jones

Assumptions





Loaded with one type of bearing at a time



A standard 120V wall outlet is available

Paint with one color per load



Customer Design Needs



Accommodate Different Sized Bearings



Fit Into Existing Fume Hood



Customer Performance Needs

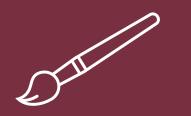


Fully Automated (except loading)

Able to load 10 bearings at a time

10

3.5 Second Cycle Time



Paint Non-Working Surface Only

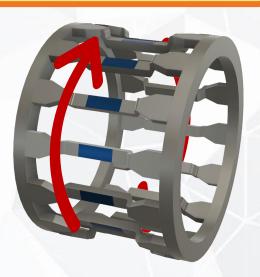


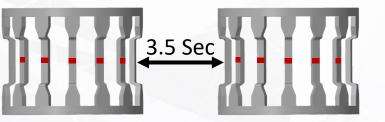
Critical Targets

Consistently paint full 360° of retainers

Cycle time of 3.5 seconds

Fit inside a pre-existing fume hood (2ft. X 3ft. X 3ft.)



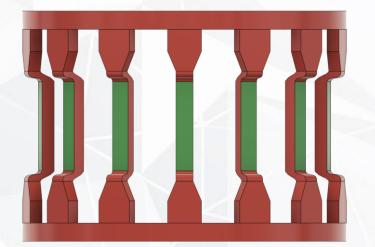




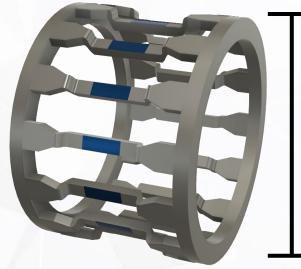


Critical Targets

Limit extraneous paint on working surface to 1 mm²



Accommodate retainers from 7/8 to 2 ½ inches in diameter



Outer Diameter



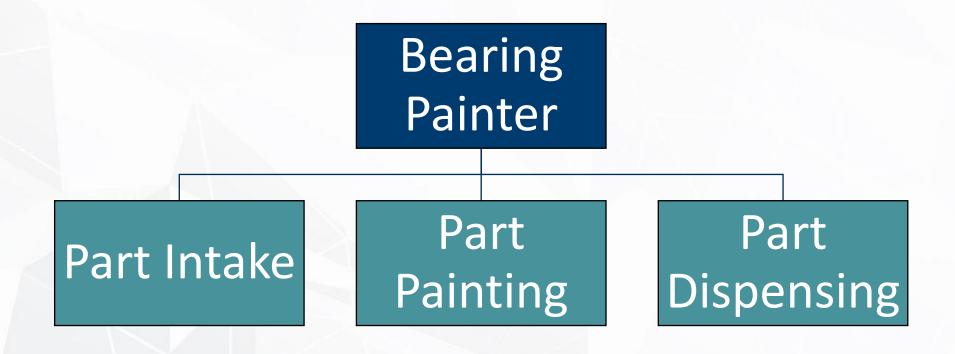
Ideation and Selection

Mason Gibson



Mason Gibson

Defined Systems





System Responsibilities

Part Intake

- Controls flow of parts into the device
- Allows for easy loading/removal

Part Painting

- Paints each part
- Pushes parts from Intake to Dispensing

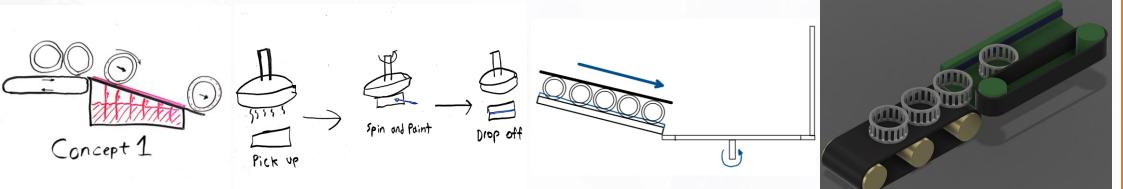
Part Dispensing

- Maintains integrity of
 - painted surfaces
- Allows for easy removal
- Signals end of cycle



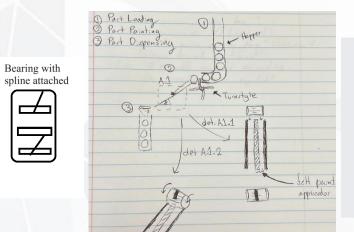
Ideation

 \square





Cylinder with retractable spline









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Selected Concept (Inverted Treadmill)



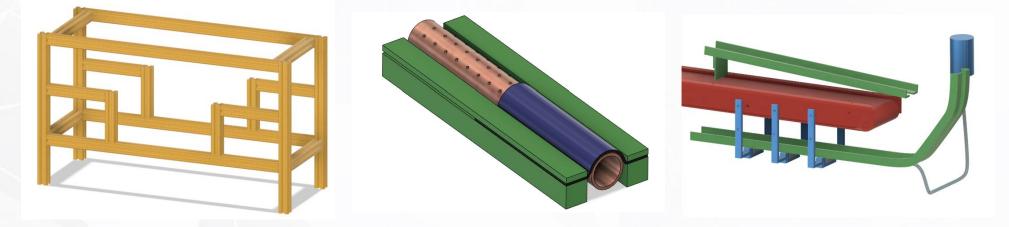
Key Features

- Parts are moved along a belt to a surface with Dykem
- Pushed along the Dykem by the bottom of the belt
- Allows for compact design



Mason Gibson

Concept Refining



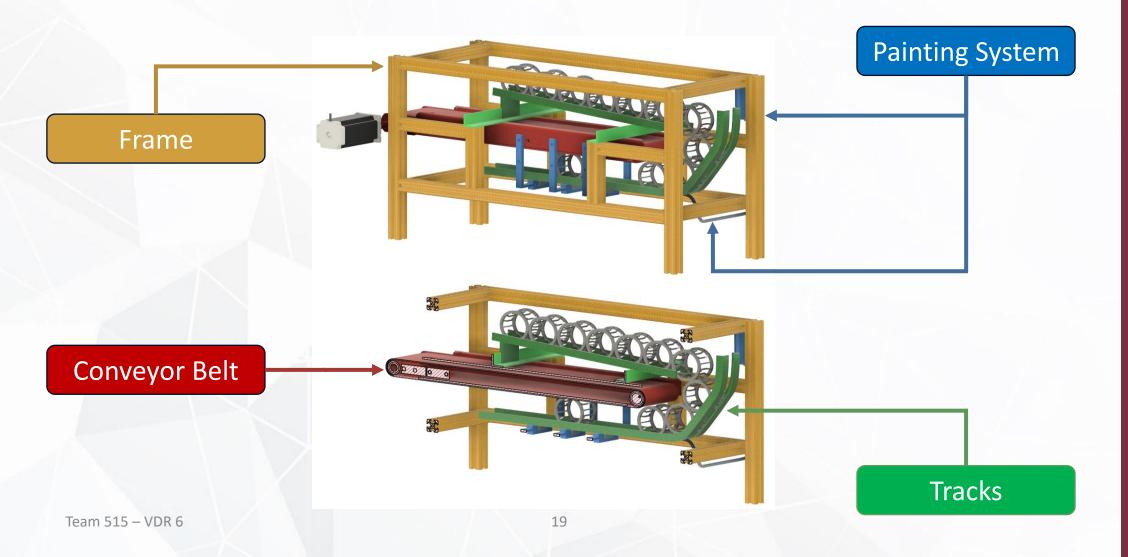
Open Frame Concept

Pressure Head Painting System

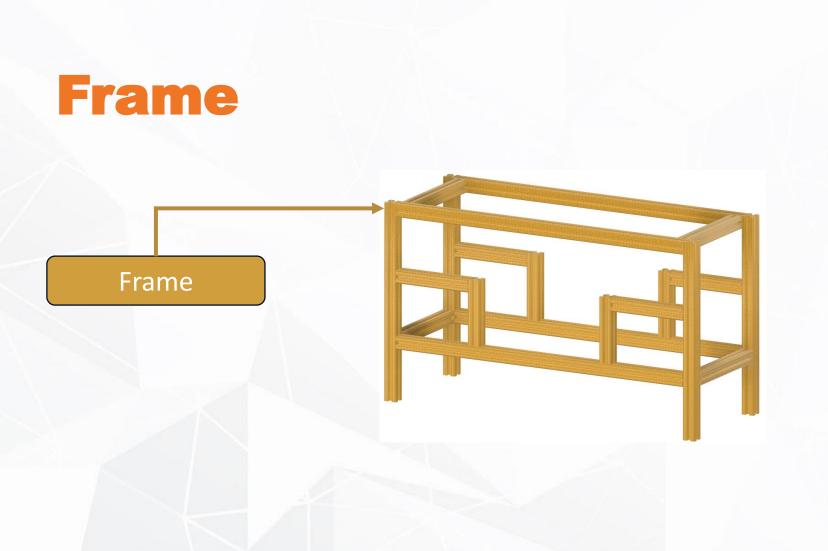
Removal of Pinch Point



Final Design Overview

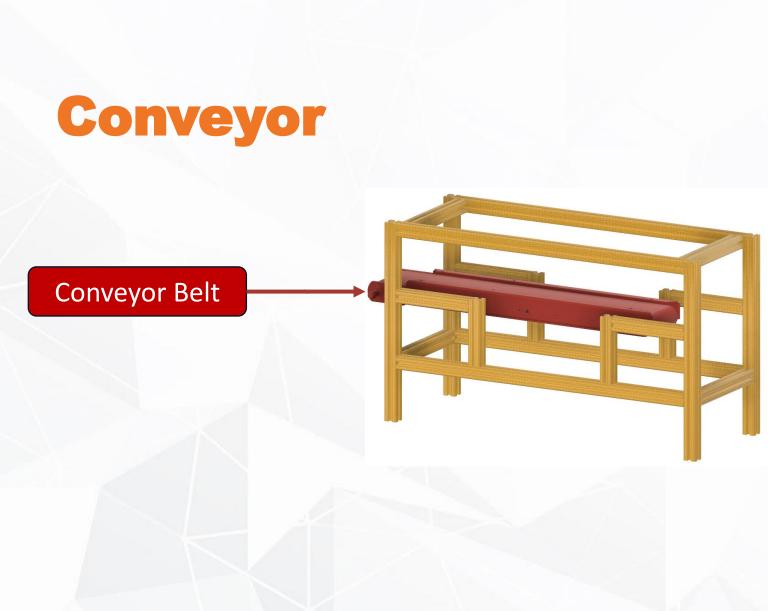






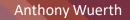












Conveyor

Conveyor Belt

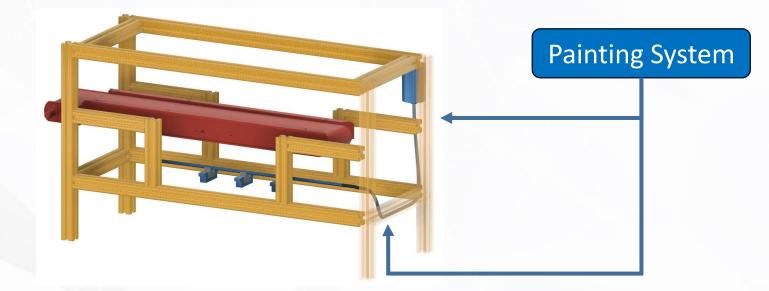
Pre-made Belt and Tensioner Assembly







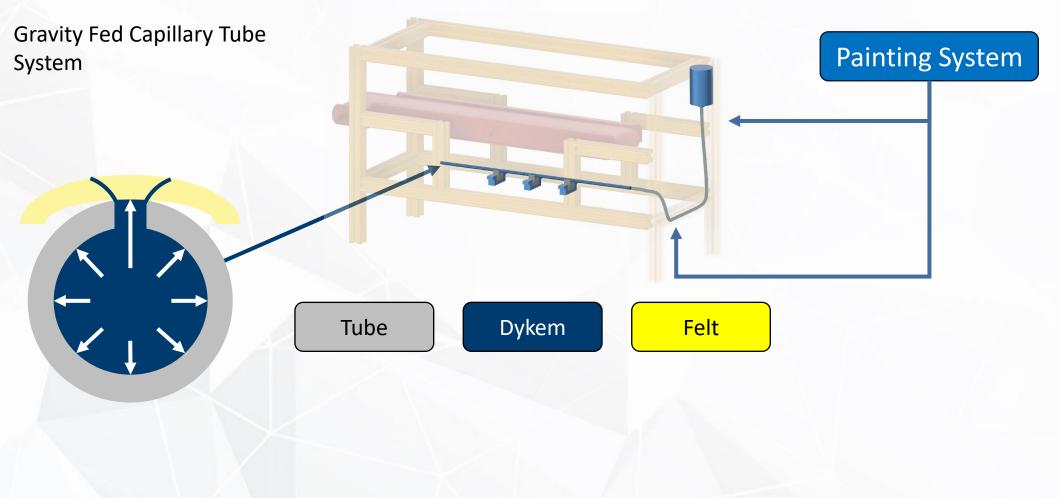
Painting System





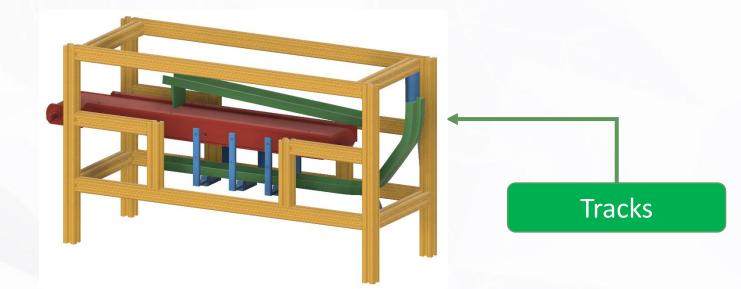
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Painting System



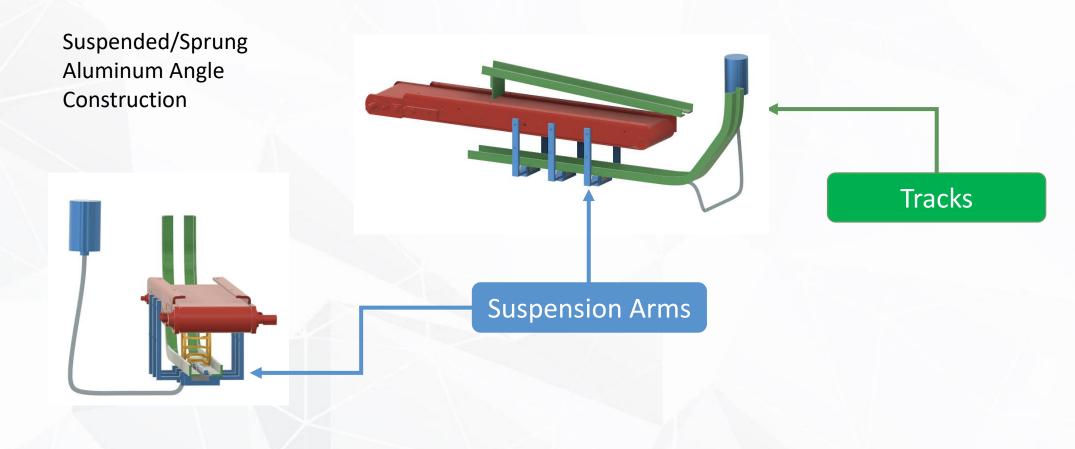


Track System



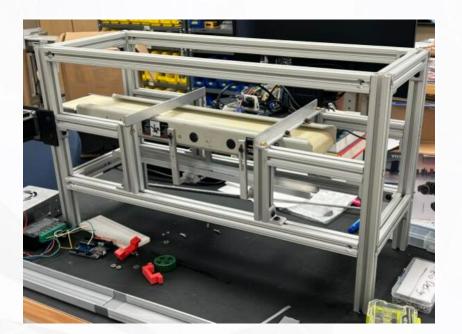


Track System





Physical Design Overview





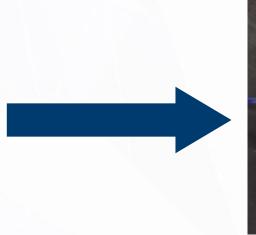
Results

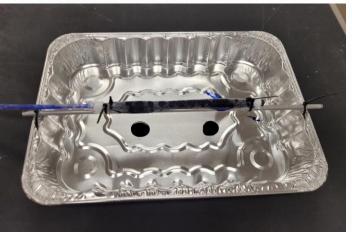
Andrew McClung



Painting System Testing









- Confirmed that the tubing is effective for painting
- Raised concern about directly connecting a bottle of Dykem to the tube



Painting System Testing

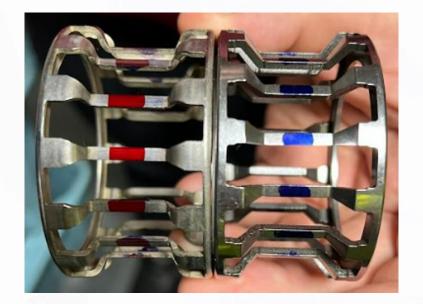




Painting System Testing



Machine Processed



Hand Painted at JTEKT



Validation	
Target	Result
Paint 360° of retainer	Continuous paint all the way around, easy to identify the color
3 ½ second cycle time	Anticipate a cycle time closer to 1.5-2.5 seconds (In the process of testing)
Limit Extraneous paint on working surface to 1 mm ²	Plan on validating next week, will run a full cycle of 10 bearings and average the results
Retainer diameters from 7/8 to 2 ½ inches	Accepts bearings from 2.97in to 0.97in (need 0.10in shim for smallest bearing)
Fit in fume hood 41in x 24in x 18in	Project dimensions are 29.5in x 15in x 14.5in, this leaves plenty of room for the user to operate

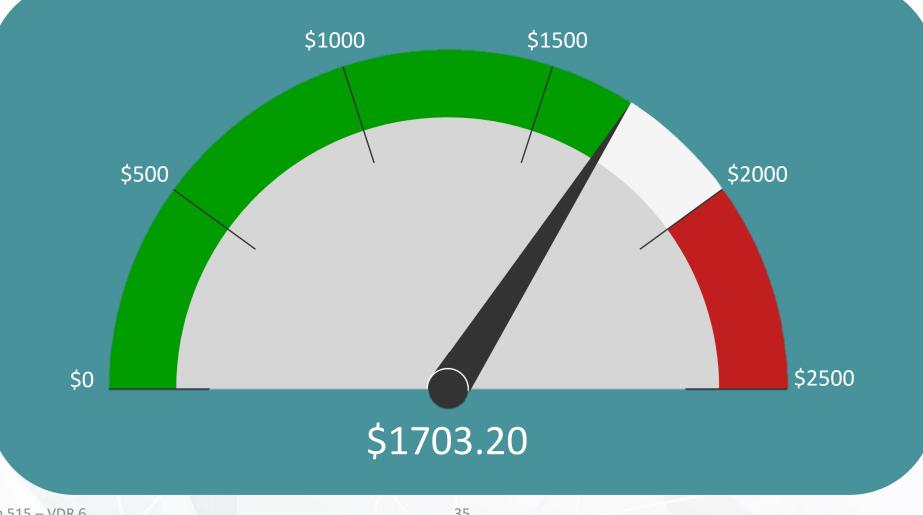


Budget

Andrew McClung



Project Budget





Project Budget \$147.90 \$139.38 \$115.92 \$1,300

- Structural Components
- Paint System Components
- Electrical Components
- Conveyor Belt



Project Budget

Name	Unit Cost	Quantity	Total
Aluminum Extrusion	\$5.30 /ft.	19 ft.	\$100.70
Corner Bracket	\$2.36	20	\$47.20
Felt Strip	\$2.59 /ft.	50 ft.	\$129.50
Aluminum Pipe	\$9.88 /ft.	1	\$9.88
AC to DC power supply	\$59.00	1	\$59.00
Stepper Motor	\$23.02	1	\$23.02
Stepper Motor Driver	\$20.00	1	\$20.00
Microcontroller	\$13.90	1	\$13.90
Conveyor Belt	~ \$1300	1	~ \$1300
			\$1703.20



Closing Content

Wesley Jean-Pierre



Team 515 – VDR 6

Incomplete Work

Part Intake

Installing intake system

Part Dispensing

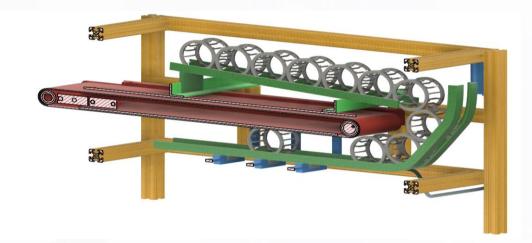
Installing dispensing system

• Electrical

Installing toggle switch

Testing

- Testing a batch of 10 bearings together
- Switching between different colors of Dykem





Wesley Jean-Pierre

Lessons Learned



Summary

Objective

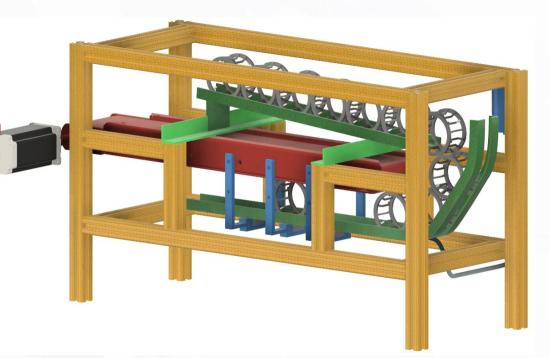
 Automate the process of painting needle bearing retainers

• Targets

 Fully operational retainer painting device under \$2000

Design

- A motor, conveyor, and track mounted to an aluminum frame, which rolls the retainers over a felt painting strip
- Outcome
 - A design that successfully paints bearing in the nonworking surface area





Wesley Jean-Pierre

Questions?





Contacts



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Wesley Jean-Pierre



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Max Jones mcj19a@fsu.edu



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Anthony Wuerth amwuerth@fsu.edu



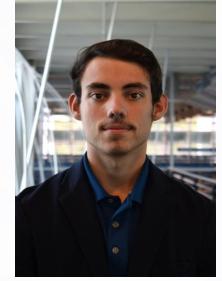


Team 515 - VDR 6









Backup Slides



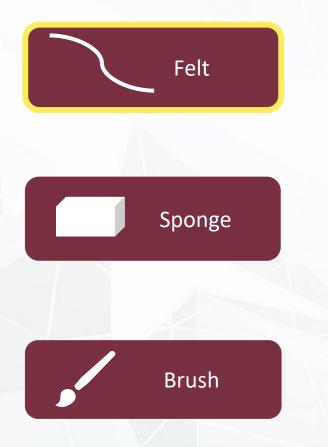
Product Budget

Name	Unit Cost	Quantity	Total
QC Conveyors IS125	~ \$1300	1	~ \$1300
Felt Strip, 2 in. wide, 1/16 in. thick	\$2.59 /ft.	50 ft.	\$129.50
1 in. x 1 in. T-slot Aluminum Extrusion	\$5.30 /ft.	19 ft.	\$100.70
Mean Well AC to DC power supply	\$59.00	1	\$59.00
Inside Corner Bracket for T-slot framing	\$2.36	20	\$47.20
NEMA 23 Stepper Motor	\$23.02	1	\$23.02
TB6600 Stepper Motor Driver	\$20.00	1	\$20.00
RexQualis Uno R3 board	\$13.90	1	\$13.90
Al 6061 1/8 in pipe	\$9.88 /ft.	1	\$9.88
515 – VDR 5	4	.5	\$1703.20



Anthony Wuerth

Testing Procedure









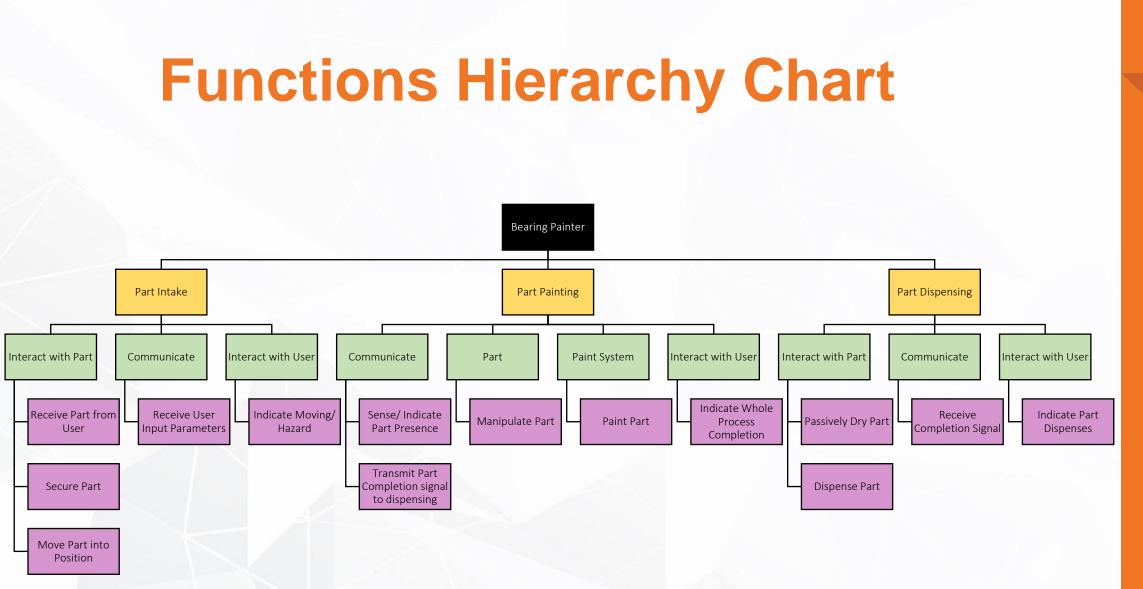
Retainer Painting

Some Customers Require Part Marking To Help Distinguish Similar Parts

- Low Production Runs
- Tedious, Manual Process
 - Operator Pulled From Position
 - Decreased Efficiency









	Binary Pairwise Comparison Chart								
Customer Requirements	1	2	3	4	5	6	7	8	Total
1. Atomated Process	-	1	0	0	0	1	0	1	3
2. Cycle Time	0	-	1	0	0	1	0	1	3
3. Paint Correct Area	1	0	-	1	1	1	1	1	6
4. Fit in Fume Hood	1	1	0	-	0	1	0	1	4
5. Process Range of Sizes	1	1	0	1	-	1	0	1	5
6. Quickly Configurable	0	0	0	0	0	-	0	1	1
7. Use Multiple Colors	1	1	0	1	1	1	-	0	5
8. Indicate Operation Status	0	0	0	0	0	0	1	-	1
Total	4	4	1	3	2	6	2	6	n - 1 = 7



Binary Pairwise Comparison

Function

- Tool to assist in ranking the importance of customer requirements
- Assigns each requirement an importance weight factor
- Requirements and weight factors assist in the development of the House of Quality

Results

The 3 most important requirements were found to be:

- 1. Paint correct area
- 2. Process range of sizes
- 3. Use multiple colors



Engineering Characteristic									
			neering		SUC		1		i
Improvement Direction	Improvement Direction		-	Î	\downarrow	Î	\downarrow	\downarrow	-
Units		Part/min	mm^2	Diameter	Sqft	Part/Load	%	%	Part/invl
Customer Requirements	Importance Weight Factor	Production Rate	Processing Accuracy	Compatibility	Size	Part Intake Limit	Automatic Operation %	Reliability	Maintenance Interval
1. Atomated Process	3	9		3	9	9	9		
2. Cycle Time	3	3	9	9		9	9	3	3
3. Paint Correct Area	6	1	9	9				1	1
4. Fit in Fume Hood	4			3	9	9			
5. Process Range of Sizes	5	1	9	9	9	3	9		
6. Quickly Configurable	1	3	3	9	3	9	3		
7. Use Multiple Colors	5	3	3		9	3	3	1	3
8. Indicate Operation Status	1	3		1		3	3	3	1
Raw Score (628)		68	144	157	156	132	120	23	31
Relative Weight %		10.83	22.93	25.00	24.84	21.02	19.11	3.66	4.94
Ra	nk Order	6	3	1	2	4	5	8	7

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House of Quality



Part Intake Limit

Automatic Operation %

Reliability

Maintenance Interval



					Concepts		1			
	Engineering Characteristics	RANDBRIG HT RB 60	Linear Processor	Inverted Treadmill	Double Conveyor	Felt Ramp	Electromagnet	Spline	Pore Track	Gravity Ramp
	Compatibility		S	S	-	S	-	S	+	+
1	Size		S	+	S	+	S	S	-	-
	Part Intake Limit	- F	S	+	S	S	S	S	S	S
	Processing Accuracy	MU	S	S	S	-	-	S	S	-
	Automatic Operation %	IAI	S	+	+	S	+	S	S	-
	Total Pluses	<u>ц</u> -	0	3	1	1	1	0	1	1
	Total Satisfactory		5	2	3	3	2	5	3	1
	Total Minuses		0	0	1	1	2	0	1	3

		Concepts			
Engineering Characteristics	Linear Procesor	Inverted Treadmill	Double Conveyor	Felt Ramp	Pore Track
Compatibility		S	S	+	-
Size		+	S	-	-
Part Intake Limit	- V	+	+	S	S
Processing Accuracy	DATUM	+	+	-	-
Automatic Operation %		+	+	S	S
Total Pluses	-	4	3	1	0
Total Satisfactory		1	2	2	2
Total Minuses		0	0	2	3



				[C] M	atrix			
		Analytical Hierarchy Process	А	А	А	А	А	
2	В	Engineering Charactersitic	Compatibility	Size	Part Intake Limit	Processing Accuracy	Automatic Operation %	Average
	В	Compatibility	1	3.000	3.000	7.000	5.000	3.800
	В	Size	0.333	1	0.333	5.000	0.333	1.400
T	В	Part Intake Limit	0.333	3.000	1	7.000	1.000	2.467
	В	Processing Accuracy	0.143	0.200	0.143	1	0.200	0.337
	В	Automatic Operation %	0.200	3.000	1.000	5.000	1	2.040
		Total	2.010	10.200	5.476	25.000	7.533	10.044
		Average	0.402	2.040	1.095	5.000	1.507	

Concept	Alternative Value
Inverted Treadmill	0.401
Double Conveyor	0.271
Felt Ramp	0.327



Analytical Hierarchy Process

Function

- Utilizes matrices to compare importance of criteria
- Criteria are Engineering characteristics & design concepts

Results

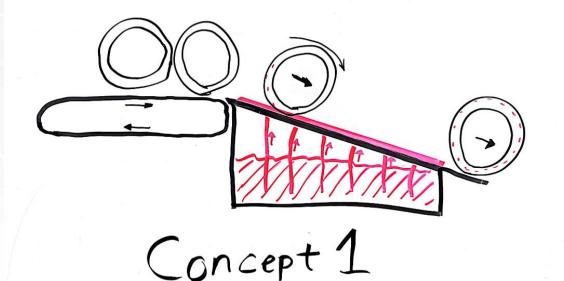
- Compatibility is the highest weighted engineering characteristic
- Inverted Treadmill with the highest rating of importance on criteria

Concept	Alternative Value
Inverted Treadmill	0.401
Double Conveyor	0.271
Felt Ramp	0.327



Mason Gibson

Medium Fidelity Concept 1

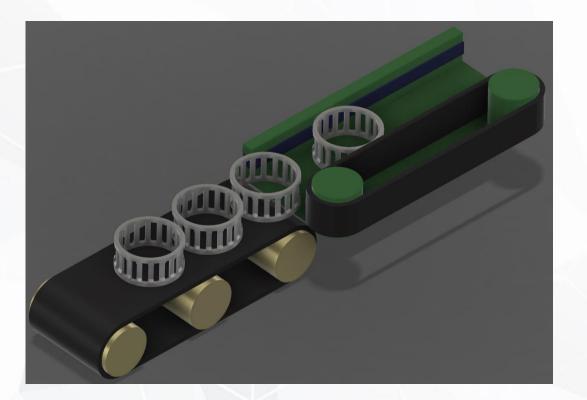


Key Features

- Conveyor belt feeds the bearings
- Bearing rolls down a ramp to be painted
- Paint felt strip fed by a reservoir of Dykem underneath



High Fidelity Concept 3 (Double Conveyor)



Key Features

- Belt brings the parts into the painting system
- One belt moves the parts along while the other side paints
- Benchmarked from a labeling machine





- This is 10-point
- This is 15-point Times
- This is 20-point
- This is 25–point
- This is 30-point
- This is 35-point
- This is 40-point
- •This is 50-point
- •This is 60-point

